

# A Strategy for Integrating a Large Finite Element Model Using MSC NASTRAN/PATRAN: X-33 Lessons Learned

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#### TECHNICAL MEMORANDUM

# A STRATEGY FOR INTEGRATING A LARGE FINITE ELEMENT MODEL USING MSC NASTRAN/PATRAN: X-33 LESSONS LEARNED

#### 1. INTRODUCTION

The responsibility for large structures rarely rests in the hands of a single institution any longer. The responsibility is now being spread across a larger number of industry partners. So too is the responsibility for the structural finite element models used for assessing these structures. This broad effort often needs to be refocused into an integrated model that reflects characteristics of the full system. This is the task of the model integrator.

Attempts have been made in the past to provide tools to the model integrator to simplify this task. ALAS¹ is an example of a tool that attempted to simplify some of the analytical aspects of the integration task. Many of today's computer-aided engineering (CAE) packages have various tools and degrees of success supporting this process. MSC/SuperModel is one of the latest tools to put forth a system for simplifying this process. All itself is based on tools developed in-house at the old McDonnell-Douglas Aircraft Corporation similar to in-house tools developed at many companies. Even with these current and developing tools most of the modelers involved in the project likely use different CAE packages. This offers its own challenges to the integrator.

For the past 3 years the Structural Dynamics and Loads Branch of NASA's Marshall Space Flight Center (MSFC) has had the task of integrating the X-33 vehicle structural finite element model. In that time, five versions of the integrated vehicle model have been produced. A great number of lessons were learned in this process. Presented here is a strategy that, if used at the outset of the project, will pave the way for a smooth integration. This strategy would benefit anyone given the task of integrating structural finite element models that have been generated by various modelers and companies. This strategy also provides benefits regardless of the tools used to help the integrator in this task.

#### 2. THE X-33 MODEL INTEGRATION PROBLEM

The X-33 vehicle is an advanced technology demonstrator sponsored by NASA. The X-33 program will demonstrate, in flight, the new technologies needed for a reusable launch vehicle using a half-scale prototype. NASA has selected Lockheed-Martin Skunkworks to design, build, and fly the X-33 test vehicle. The industry team, with Lockheed-Martin Skunkworks as lead, includes Lockheed-Martin Michoud, B.F. Goodrich (previously Rohr), Boeing Rocketdyne, and NASA.

The X-33 has a complicated and highly coupled structural design (see fig. 1). It consists of a liquid oxygen (lox) tank sitting on top of a pair of side-by-side liquid hydrogen (LH<sub>2</sub>) tanks. Behind and in-between the hydrogen tanks are the two aerospike engines. Over all of this is a complex aeroshell structure that provides thermal protection and the aerodynamic shape of the lifting body. The canted and vertical fins and body flaps are also attached to the thrust structure.

In order to assess the design, an integrated vehicle finite element model was required to determine internal loads. These internal loads were derived from externally applied forces in both static and transient dynamic loads analyses. The required model was generated from individual major structure models obtained from across the industry team. Models of the LH<sub>2</sub> tanks, thrust structure, intertank, and landing gears were provided by Lockheed-Martin Skunkworks. The lox tank model was provided by Lockheed-Martin Michoud. The aerospike engine model was provided by Boeing Rocketdyne. B.F. Goodrich provided models of the canted fin control surfaces. The Structural Dynamics and Loads Branch of NASA's MSFC had the task of modeling the aeroshell, body flap control surfaces, canted and vertical fins, and the rotating launch mount. The Structural Dynamics and Loads Branch also had the task of integrating the various models into the full vehicle model.

The integrated vehicle model that resulted has had five versions. Four complete loads analysis cycles have been completed. These include static prelaunch, ascent, descent, landing, and transient liftoff analyses. A fifth loads cycle is underway. The models have also been used to assess dynamic characteristics for flight control analyses. The model grid count peaked at 29,427 grids for load cycle 4 and is now down to 20,400 grids for load cycle 5 after a concerted effort to reduce the model size.

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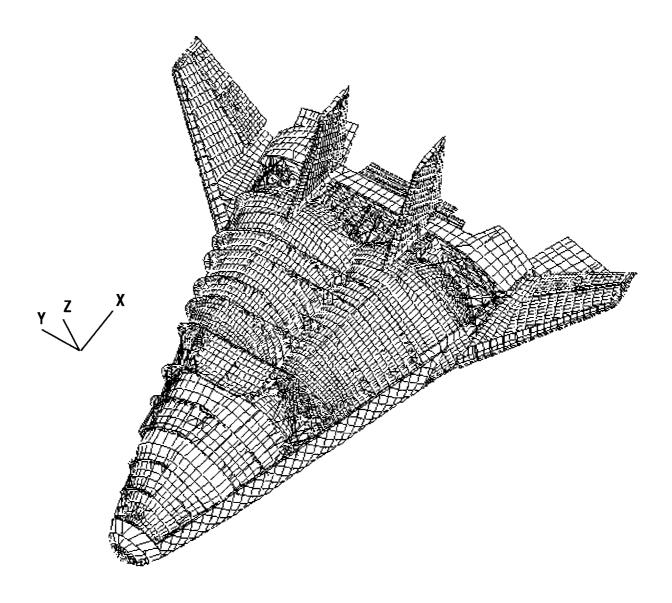


Figure 1. Cut-away view of X-33 structural finite element model.

#### 3. STRATEGY FOR MODEL INTEGRATION

The strategy presented here consists of six decisions that need to be made at the outset of the project. These decisions, once made and agreed to by the modeling team, will pave the way for a smooth model integration. These six decisions are: purpose of model, units, common material list, model numbering, interface control, and archive format. Each is discussed in detail below.

#### 3.1 Purpose of Model

The first decision to be made is the purpose of the model. Is it a stress model? Is it a loads model? A dynamics model? This decision drives many of the following decisions. In particular, it defines the scope of the model and therefore the approach to the modeling. It would also have a direct impact on the size of the model. The effort for X–33 was to develop a model that would be used to recover internal element forces for use by stress analysts. It was never intended to recover stresses, as this would have led to a model that would be all but impossible to run. It was also meant to adequately represent elastic modes from 0 to  $\approx$ 25 Hz so that liftoff transient loads could be recovered. These dynamic characteristics were also to be used for control stability studies and POGO analyses. During the entire development of the model it was a continual challenge to balance the need for accurate forces (not stresses) and dynamics and still have a reasonably sized model. Accommodations also had to be made, both in increased and decreased fidelity, when it was decided the model would also be used for flutter analyses.

It should be noted here that on the X-33 project two model "styles" existed. One style of modeling consisted of modeling the structure the way it was intended to work; i.e., modeling web caps with rod elements because they were primarily intended to carry axial load. The other style modeled the structure the way it was drawn or built in order to verify the assumptions used in design. For example, the web caps were modeled with bar elements to verify that the axial load was the only significant load. Every modeler uses a combination of these styles. The reasons include preference, economy, time, and maturity of design. There is little expectation that the modeling can be controlled to the point of requiring a consistent style. However, the model integrator needs to be aware of these styles so that any issues that come up because of them can be quickly recognized and settled.

#### 3.2 Units

The units of measure the model will use need to be decided. This could be of great importance if the model is a joint venture between European and U.S. modelers. Even if the standard units used by the modelers are similar, care should be taken, especially with mass versus weight units. While in the U.S. most aircraft modelers commonly using inches, density poses a problem. Many modelers use weight density but also, many modelers use mass density. The desired units for the integrated model should be decided very early so the individual modelers can accommodate this. This was not done on the X–33, so a number of models had to have their densities converted. Fortunately, all models were in inches.

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#### 3.3 Common Materials List

The next thing to determine is material properties. It would be very advantageous to establish a common materials list for use by all the modelers. The advantage would be a consistent set of properties between modelers and therefore no redundancy in material definitions. Even though the materials might be standard, there are many variations in alloys and thermal characteristics. This list would obviously grow and change as the design evolves, but it should be a simple matter to provide regular updates. Even if a particular model needed some specialized properties, it would start with a common base.

In conjunction with the common materials list, the ambient temperature of each model should be defined. This could have a large effect on the material properties used for that model. For example, composite material properties are much more dependent on temperature than metals, but even aluminum has significant changes at cryogenic temperatures, such as the lox tank for the X–33. Also thermal protection materials drastically change properties over their expected temperature ranges. Several different material definitions may be necessary for the same material because of its use in different areas. For example, a composite material may be used in a cryogenic LH<sub>2</sub> tank and also a hot thermal protection support beam and therefore have two different material definitions. A common reference temperature and units for coefficients of thermal expansion should also be established to facilitate a thermal contraction or expansion assessment.

The use of a common materials list would also allow for easier changing of material properties for assessment of different temperature profiles of the integrated model. For example, the ascent temperature profile of the X-33, and therefore its material properties, may be drastically different from the descent profile. You may therefore have a different common materials list for each temperature profile with the same material identification. These lists could then be exchanged to assess the model for the different profiles.

Invariably, somewhere, the model will use a "stiff" bar or plate where an RBAR won't do or use stiff springs to recover interface loads in the global coordinate system. It would be good to define these materials and properties in the common materials list also, so all the modelers could be consistent and reduce redundant definitions.

The value of the MSC/NASTRAN parameter K6ROT for drilling stiffness in shell elements should be decided early. Some modelers depend on a large value of K6ROT to alleviate drilling stiffness problems. Others depend on zero or low values of K6ROT to allow some freedom in this direction. Even if you can specify different K6ROT parameters for different NASTRAN superelements, it is a good idea to specify a default value so the modelers may accommodate it with other techniques.

Neither the common materials list or temperature profiles were established for the X-33 model, and this has caused a certain amount of aggravation throughout its evolution. Such a list would also be of great benefit to model correlation efforts at a later date. It may still be necessary to go back and establish this list, but it would have been much easier to have established it from the start.

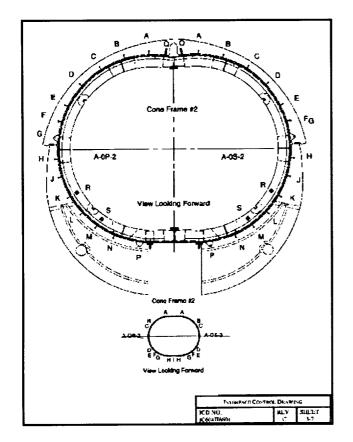
#### 3.4 Model Numbering

Assigning node number ranges to the different models is fairly common practice. You may want to specify a target number of grids to help limit the size of the model, but be sure to allow adequate room for inevitable growth. Enforce the numbering not only on nodes but also elements, properties, rigid elements, and multipoint constraints (MPC's). Rigid elements and MPC's can cause difficulties. MSC/NASTRAN and MSC/PATRAN sometimes treat them as elements and sometimes treat them as separate entities. This can particularly be a problem if you later decide to use superelements. Older versions of MSC/NASTRAN would allow an element and a rigid element to have the same number in a standard analysis but not in a superelement analysis. To be safe, make sure their numbering is exclusive of the elements. The material numbering should be from the common materials list but if a special material is needed, enforce the numbering range. And finally, make the ranges different enough so that you can easily identify the model that an element, node, or property belongs to.

#### 3.5 Interface Control

If at all possible, an Interface Control Document (ICD) should be established for the different model pieces. This is a document that defines the interface geometry and loads between different portions of the model or structure. For the most part, these data are already contained in structural ICD's. For the X-33, this was true for interfaces between companies such as B.F. Goodrich and Lockheed-Martin Skunkworks or Lockheed-Martin Michoud and Lockheed-Martin Skunkworks, Lockheed-Martin Michoud's ICD (fig. 2) was particularly well done and was invaluable in interfacing the lox tank model with other models. Much of the X-33 was designed within the same company and did not have a structural ICD. It would be very beneficial to establish such ICD's for the purpose of the models, even if they are not rigidly controlled documents. They might also help define better divisions of responsibility for the model pieces. An example for the X-33 would be the aeroshell ring frames over the  $LH_2$  tanks. The ring frames' modeling responsibility belonged to the aeroshell modeler and the tank modeling responsibility to another. Since the ring frames attached continuously to the tanks, a great deal of coordination was required to make the model meshes match. A better approach might have been to let the tank modeler model the ring frames and define an ICD for the frame to aeroshell interface. This would still require coordination, but the interface would be better defined and more along structural lines rather than model meshes.

In instances where the interface between structures should only pass loads or allow compliance in certain directions, the ICD should carefully indicate which side these releases are modeled. The structural ICD should make this clear; however, many modelers that are only concerned with one side of the interface will not make any provisions for special releases except through model constraints. These constraints are then lost upon integration and it is left to the integrator to fix the problem, usually with springs or rigid elements. This is not necessarily the most efficient method. This problem occurred regularly on the X–33 project.



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Figure 2. Sample from Lockheed-Martin Michoud's ICD 1.

#### 3.6 Archive Format

The format for storing and transmitting the model data needs to be decided. For the X–33, this was decided to be the MSC/NASTRAN bulk data. This decision was made for two primary reasons. First, because the modeling effort spanned several companies that used various CAE packages, even different versions of those packages, the bulk data was deemed the most portable. MSC/NASTRAN was the most common denominator. Second, even though the CAE translators to MSC/NASTRAN are continually improving, they are not perfect. Since these models would be passed back and forth many times and passed through CAE translators multiple times, it was decided that the bulk data would be the trusted copy. Any modifications that were made with the help of the CAE packages would be output to MSC/NASTRAN but then text edited into the archive bulk data format. In fact, for X–33, most errors between model versions were traced back to passes through the CAE packages where beam orientations, section properties, and material definitions were compromised. Bulk data comments could also be preserved with this cut-and-paste method.

For X-33, it was also decided that the separate models would remain in separate files and assembled using "include" statements in the MSC/NASTRAN analysis file. This provided ease of updates for portions of the model that were in various stages of flux and design. A submodel's included bulk data file could easily be replaced with a new one as updates were made without affecting the rest

of the model. Also, had the common materials list been used, this would be a convenient way of using it. This decision, as beneficial as it was, created one problem—MSC/NASTRAN does not allow duplicate grid definitions. This prohibited having grid definitions in both bulk data files for models that interfaced. However, the CAE packages cannot read in the bulk data for a submodel without this grid definition. For example, SDRC IDEAS would not read in any of the file if there was such an error, while MSC/PATRAN would not read in affected elements but would read the rest of the file.

One suggestion for handling this problem was that each submodel have completely unique grid numbers and then have an additional interface file that contained connecting springs or rigid elements. This could be an effective method for a relatively simple model with few interfaces, but for this highly coupled structure, the cost of additional grids and elements would be prohibitive. Also, it would be very difficult to ensure absolutely coincident grid points that are required for this method to work correctly.

The solution decided on for the X-33 was that within a submodel bulk data file all grid definitions that interfaced with other submodels would be placed in the bottom of the bulk data file where they could be easily found (fig. 3). Further, the bulk data files would be considered in an upstream/downstream fashion similar to superelements. The submodel bulk data files were named with a preceding number to facilitate this upstream/downstream ordering. An interface grid was defined once in an upstream bulk data file. When it was referenced in a downstream bulk data file, its definition would be commented out with a unique integration comment such as "\$INTEG \$." Thus, when all bulk data files were included in the MSC/NASTRAN analysis file, no duplicate grid definitions would result. If it was necessary to read a bulk data file into a CAE package or have a checkout analysis done by itself, then all occurrences of the "\$INTEG \$" comment would be changed to nothing in a text editor first.

#### 4. USE OF MSC/PATRAN IN MODEL INTEGRATION

MSC/PATRAN was the CAE package used for the model integration. This was a difficult task made relativly easy by several of MSC/PATRAN's features associated with creating and displaying groups. Lockheed-Martin Michoud reported great difficulty completing similar tasks with SDRC IDEAS. In particular, MSC/PATRAN offered a unique benefit to this integration process. With the submodel bulk data files defined as they were, they could be read into MSC/PATRAN to form an integrated model database, as long as the files were read in the proper order. This could be done without having to edit out the "\$INTEG \$" comments. In addition, this process was vastly aided by the use of a journal file. The journal file was constructed to create a group, set it as default, and then read the bulk data and repeat for the next file. With this journal file it was extremely easy to reconstruct integrated model databases for viewing results. It was also very easy to establish an X–33 template for use by other engineers. For the other companies that used MSC/PATRAN, but had different versions on different machines, this was a convenient way of providing them with a database.

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Majority of model, including grids that do not interface with any other models.

Interface grids to downstream bulk data files. This is the first time they are defined for the NASTRAN analysis. They are part of this submodel but grouped here for convenience.

Interface grids to upstream bulk data files. They are commented out to avoid conflict in the NASTRAN analysis. They can easily be uncommented for standalone analysis or standalone PATRAN database.

Figure 3. Sample of bottom portion of a submodel bulk data file.

#### 5. PITFALLS ENCOUNTERED WITH MSC/PATRAN

The largest MSC/PATRAN pitfall encountered lies in the association in the database of the beam orientation vectors with the property rather than the element. The X-33 model has a large number of beam elements with the same cross-sectional properties but different orientations. The orientations were not easily defined by an MSC/PATRAN field, so a different property was required for each while defining them in the database. These were later text edited in the bulk data file to reference the same property card. On reading this bulk data file back into MSC/PATRAN, the property remained a single property entry with a MSC/PATRAN spreadsheet field for the orientation. This was convenient when checking beam properties. However, when it was desired to add a new beam based on the existing property, the output beam orientation was undefined and had to be text edited later in the bulk data file.

Another pitfall was described in section 3.5, regarding translation between the CAE package and the bulk data. Even MSC/PATRAN and MSC/NASTRAN had this problem, although it was worse with other CAE packages. In fact, for the X–33, most errors between model versions were traced back to passes through the CAE packages where beam orientations, section properties, and material definitions were compromised.

One other pitfall occured regarding the translating of the bulk data into MSC/PATRAN. This problem came with the switch from MSC/PATRAN 6.2 to MSC/PATRAN 7.0. The model contained a set of MPC's that were defined on multiple MPC cards but had the same MPC number. MSC/NASTRAN handles this very well. MSC/PATRAN reads each of the separate cards and then internally offsets the MPC identification for each one. This particular offset is not user controllable. In version 6.2 this offset is fixed at 1, which caused no problem. In version 7.0 the fixed offset was changed to 10,000. This caused the offset numbers to clash with other rigid element entities. Fortunately, the journal file could be reordered somewhat to avoid this problem.

#### 6. CONCLUSION

The task of integrating a structural finite element model that has been developed by several modelers from several companies is challenging. This task has unquestionably benefited from all the tools made available through the currently available CAE packages. There are, however, strategies that can be brought to bear that can smooth the process greatly. Even with many of these strategies now being included in the next generation of CAE packages, the model integrator's understanding of them is essential. This is particularly true with the variety of sources of models being integrated. These strategies are best used early in the project to lay a good foundation for integration. A strategy has been presented here that consists of six decisions that need to be made: purpose of model, units, common materials list, model numbering, interface control, and archive format. This strategy has been proved and expanded from experience on the X–33 vehicle.

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The X-33 vehicle is an ac	dvanced technology demo	nstrator sponsored by N	ASA. For the past
3 years the Structural Dyn	namics and Loads Branch	of NASA's Marshall Sp	ace Flight Center
has had the task of integra	ating the X–33 vehicle str	uctural finite element m	odel. In that time,
five versions of the integr	ated vehicle model have b	peen produced and a stra	itegy has evolved
that would benefit anyone	given the task of integrat	ing structural finite eler	nent models that have
been generated by various	s modelers and companies	i. The strategy that has b	een presented here
consists of six decisions to model numbering, interface	nat need to be made: purp ce control, and archive for	ose of models, units, co	mmon materials list,
expanded from experience	e on the X–33 vehicle	mat. This strategy has t	been proven and
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